

JORDAN DERIVATIONS ON LIE IDEALS OF σ -PRIME RINGS

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ABSTRACT

In this paper we prove that, if U is a σ -square closed Lie ideal of a 2-torsion free σ -prime ring R and $d: R \rightarrow R$ is an additive mapping satisfying $d(u^2) = d(u)u + ud(u)$ for all $u \in U$ then $d(uv) = d(u)v + u d(v)$ holds for all $u, v \in U$.

Keywords: Lie ideal, σ -square closed Lie ideal, σ -prime ring, Jordan derivation, derivation.

1. Introduction

Throughout the paper, we consider R to be an associative ring with centre Z . $[a, b] = ab - ba$ which denotes the commutator of a and b , we will use the identities: $[ab, c] = [a, c]b + a[b, c]$ and $[a, bc] = [a, b]c + b[a, c]$ for all $a, b, c \in R$. An additive subgroup U of R is called a Lie ideal if $[U, R] \subseteq U$. An additive mapping $d: R \rightarrow R$ is called a derivation if $d(ab) = d(a)b + ad(b)$ holds for all $a, b \in R$ and it is called a Jordan derivation if $d(a^2) = d(a)a + ad(a)$ holds for all $a \in R$. Clearly every derivation is a Jordan derivation but the converse is not true in general. A ring R is said to be a prime ring if $aRb = 0$ ($a, b \in R$) implies that $a = 0$ or $b = 0$. An additive mapping $f: R \rightarrow R$ is called a generalized derivation with the associated derivation $d: R \rightarrow R$ if $f(ab) = f(a)b + ad(b)$ holds for all $a, b \in R$; it is called a Jordan generalized derivation with the associated derivation d of R such that $f(a^2) = f(a)a + ad(a)$ holds for all $a \in R$. R. Awtar [1] proved that if $U \not\subseteq Z$ is a square closed Lie ideal of a 2-torsion free prime ring R and $d: R \rightarrow R$ is an additive mapping such that $d(u^2) = d(u)u + ud(u)$ for all $u \in U$ then $d(uv) = d(u)v + u d(v)$ holds for all $u, v \in U$.

We need the following lemmas due to R. Awtar [1] for proving our result.

Lemma 1.1 If $U \not\subseteq Z$ is a Lie ideal of a ring R , then $d(uv + vu) = d(u)v + ud(v) + d(v)u + vd(u)$ holds for all $u, v \in U$.

Lemma 1.2 If $U \not\subseteq Z$ is a Lie ideal of a ring R , then $d(uvu) = d(u)vu + ud(v)u + uvd(u)$ holds for all $u, v \in U$.

Lemma 1.3 If $U \not\subseteq Z$ is a Lie ideal of a ring R , then $d(uvw + wvu) = d(u)vw + ud(v)w + uvd(w) + d(v)vu + wd(v)u + wvd(u)$ holds for all $u, v, w \in U$.

Lemma 1.4 If $U \not\subseteq Z$ is a Lie ideal of a ring R , then $u^v[u, v] = 0$ holds for all $u, v \in U$, where $u^v = d(uv) - d(u)v - u d(v)$.

Lemma 1.5 If $U \not\subseteq Z$ is a Lie ideal of a ring R , then $[u, v]u^v = 0$ for all $u, v \in U$, where u^v is as in Lemma 1.4

2. Jordan Derivations on Lie Ideals of σ -Prime Rings

Let R be a ring. A mapping $\sigma: R \rightarrow R$ is called an involution if $\sigma(\sigma(a)) = a$ and $\sigma(ab) = \sigma(b)\sigma(a)$ holds for all $a, b \in R$. A Lie ideal U of R is called a σ -Lie ideal if $\sigma(U) = U$ and it is called a σ -square closed Lie ideal if it is a σ -Lie ideal and for all $u \in U, u^2 \in U$. A ring R with involution σ is said to be a σ -prime ring if $aRb = aR(\sigma(b)) = \{0\}$ implies that $a=0$ or $b=0$. It is worthwhile to note that every prime ring having an involution σ is σ -prime but the converse is not true in general. As an example, let $T = R \times R^o$, where R^o is an opposite ring of a prime ring R with involution $\sigma(x, y) = (y, x)$. Then T is not prime if $(0, a)T(a, 0) = 0$. But, R is σ -prime if we set $(a, b)T(x, y) = 0$ and $(a, b)T(\sigma((x, y))) = 0$, then $aRx \times yRb = 0$ and $aRy \times xRb = 0$ and thus $aRx = yRb = aRy = xRb = 0$ by Oukhtite and Salhi [6]. We define the set $S_{\sigma}(R) = \{x \in R: \sigma(x) = \pm x\}$ which are known as the set of symmetric and skew symmetric elements of R . Let U be a Lie ideal of R . We define $C_R(U) = \{r \in R: ru = ur, \forall u \in U\}$ which we shall call the centralizer of U with respect to R . Oukhtite and Salhi [12] worked on left derivation on σ -prime rings and proved that $U \subseteq Z$ or $d(U) = 0$, where U is a nonzero σ -square closed Lie ideal of R . Oukhtite and Salhi [12] described additive mappings $d: R \rightarrow R$ such that $d(u^2) = 2ud(u) \forall u \in U$, where U is a nonzero σ -square closed Lie ideal of a 2-torsion free σ -prime ring R and prove that $d(uv) = ud(v) + vd(u)$ for all $u, v \in U$. Afterwards, Oukhtite, Salhi and Taoufiq [11] studied Jordan generalized derivations on σ -prime rings and proved that every Jordan generalized derivation on U of R is a generalized derivation on U of R , where U is a σ -square closed Lie ideal of a 2-torsion free σ -prime ring R . Some significant results on Lie ideals and generalized derivations in σ -prime rings have been obtained by M. S. Khan and M. A. Khan [5]. On the other hand, various remarkable characterizations of σ -prime rings on σ -square closed Lie ideals have been studied by many authors viz. M. R. Khan, D. Arora and M. A. Khan [4]; Oukhtite and Salhi [7, 8, 9, 10] and J. Bergun, I. N. Herstein and J. W. Kerr [2] and I. N. Herstein [3]. In this paper, we shall prove that if $d: R \rightarrow R$ is an additive mapping satisfying $d(u^2) = 2ud(u) \forall u \in U$, where U is a σ -square closed Lie ideal of a 2-torsion free σ -prime ring R then $d(uv) = ud(v) + vd(u)$ for all $u, v \in U$ and hence every Jordan derivations on a σ -prime ring R is a derivation on R . We begin with the following results.

Lemma 2.1 Let R be a 2-torsion free σ -prime ring and U be a σ -Lie ideal of R . Let $u \in U$ be any element such that $[u, [u, x]] = 0$, for all $x \in R$, then $[u, x] = 0$.

Proof: We have $[u, [u, x]] = 0$ for all $x \in R$. Let $y \in R$, then $xy \in R$. Replacing x by xy , we have $[u, [u, xy]] = 0$. So $0 = [u, [u, xy]] = [u, x[u, y]] + [u, x]y$

$$\begin{aligned}
&= [u, x\{u, y\}] + [u, [u, x]y] \\
&= x\{u, [u, y]\} + [u, x]\{u, y\} + [u, x]\{u, y\} + [u, [u, x]]y \\
&= 2[u, x]\{u, y\}.
\end{aligned}$$

Since R is 2-torsion free so $[u, x]\{u, y\} = 0$. For every $z \in R$ we have $zy \in R$. Putting zx for y , we have $[u, x]\{u, zx\} = 0$. Therefore, $0 = [u, x]\{z[u, x] + [u, z]x\}$

$$\begin{aligned}
&= [u, x]z[u, x] + [u, x]\{u, z\}x \\
&= [u, x]z[u, x].
\end{aligned}$$

Therefore, $[u, x]R[u, x] = 0$. Since $\sigma(U) = U$, we have $\sigma(u) = u$, for all $u \in U$. Let $x \in S_{\sigma\sigma}(R)$. Then $\sigma(x) = \pm x$. If $\sigma(u) = u$ and $\sigma(x) = -x$, then

Hence $[u, x]R[u, x] = [u, x]R[\sigma(u, x)] = 0$. By the σ -primeness of R , we get $[u, x] = 0$.

Lemma 2.2 Let R be a 2-torsion free σ -prime ring and $U \neq 0$ be a σ -Lie ideal and a σ -subring of R . Then either $U \subseteq Z$ or U contains a nonzero σ -ideal of R .

Proof: First we assume that, U as a σ -ring is not commutative. Then for some $u, v \in U$, $[u, v] \neq 0$ and $[u, v] \in U$. Therefore the ideal J of R generated by $[u, v]$ is nonzero, $J \subseteq U$ and $\sigma(J) = J$. On the other hand, let us assume that U is commutative. Then for every $u \in U$, $[u, [u, x]] = 0$ for all $x \in R$. Hence by Lemma 2.1, $[u, x] = 0$. This shows that $U \subseteq Z$.

Lemma 2.3 If $U \not\subseteq Z$ is a σ -Lie ideal of a σ -prime ring R , then $C_R(U) = Z$.

Proof: $C_R(U)$ is both a σ -subring and a σ -Lie ideal of R and $C_R(U)$ contains no nonzero σ -ideal of R . In view of Lemma 2.2, $C_R(U) \subseteq Z$. Therefore, $C_R(U) = Z$.

Lemma 2.4 If U is a σ -Lie ideal of a σ -prime ring R and $a \in R$. If $[a, [U, U]] = 0$ then $[a, U] = 0$, that is, $C_R([U, U]) = C_R(U)$.

Proof: If $[U, U] \not\subseteq Z$, then by Lemma 2.3, $a \in Z$, so a centralizes U . On the other hand, let $[U, U] \subseteq Z$, then we have $[u, [u, x]] = 0$ for $u \in U$ and $x \in R$. In view of Lemma 2.1, $[u, x] = 0$. This yields that $U \subseteq Z$. For both the cases we have seen that $a \in C_R(U)$. This gives that $C_R([U, U]) = C_R(U)$.

Lemma 2.5 Let $U \not\subseteq Z$ be a σ -square closed Lie ideal of a 2-torsion free σ -prime ring R and $d: R \rightarrow R$ be an additive mapping satisfying $d(u^2) = d(u)u + u d(u)$, for all $u \in U$. If $u^v = d(uv)u - u d(v)$, for all $u, v \in U$ then $u^v w[u, v] = 0$, for all $w \in U$.

Proof: In view of Lemmas 1.4 and 1.5, we have $[u^v, [u, v]] = u^v[u, v] - [u, v]u^v = 0$. This yields that $u^v \in C_R([U, U]) = C_R(U)$, by Lemma 2.4. Hence for every $w \in U$, we have $u^v w[u, v] = 0$.

Lemma 2.6 ([7], Lemma 2.2) Let $U \not\subseteq Z$ be a σ -Lie ideal of a 2-torsion free σ -prime ring R and $a, b \in R$ such that $aUb = aU((b) = 0$, then $a = 0$ or $b = 0$.

Theorem 2.7 Let U be a σ -square closed Lie ideal of a 2-torsion free σ -prime ring R and $d: R \rightarrow R$ be an additive mapping satisfying $d(u^2) = d(u)u + u d(u)$, for all $u \in U$, then $d(uv) = d(u)v + u d(v)$ holds for all $u, v \in U$.

Proof: If U is a non-commutative Lie ideal of R then $U \not\subseteq Z$. By Lemma 2.5, we have $a^b w [a, b] = 0$ for all $a, b, w \in U$. Let us assume that $a, b \in U \cap S_{\sigma\sigma}(R)$. Since $((U) = (U)$, we have $(([a, b] = [a, b])$ as $[a, b] \in U$. If $((b) = 1b$ and $((a) = a$, then

Also, if $((b) = b$ and $((a) = 1a$, then $(([a, b] = [a, b])$. Therefore, we have $a^b w [a, b] = a^b w (([a, b] = 0$. By applying the Lemma 2.6 in the above relation, we obtain that $a^b = 0$ or $[a, b] = 0$ for all $a, b \in U \cap S_{\sigma\sigma}(R)$. Let $I_a = \{b \in U : a^b = 0\}$ and $J_a = \{b \in U : [a, b] = 0\}$. Then I_a and J_a are additive subgroups of U such that

. Then by Brauer's trick $I_a = U$ or $J_a = U$. Using the similar argument, we have $U = \{a \in U : U = I_a\}$ or $U = \{a \in U : U = J_a\}$. If $U = \{a \in U : U = J_a\}$ then $[a, b] = 0$, which yields that $U \subseteq Z$, by Lemma 2.2. Which is a contradiction to the fact that $U \not\subseteq Z$. So we have $U = \{a \in U : U = I_a\}$ and hence $a^b = 0$ for all $a, b \in U \cap S_{\sigma\sigma}(R)$.

This implies

$$d(ab) = d(a)b + ad(b), \forall a, b \in (U \cap S_{\sigma\sigma}(R)) \dots \dots \dots (1)$$

Now let $u, v \in U$. If we define $u_1 = u + ((u)$, $u_2 = u - ((u)$, $v_1 = v + ((v)$, $v_2 = v - ((v)$. Then $u_1, u_2, v_1, v_2 \in U \cap S_{\sigma\sigma}(R)$ and we have $2u = u_1 + u_2$, $2v = v_1 + v_2$. Therefore, in view of (1), we obtain

$$\begin{aligned} d(2u2v) &= d(u_1 v_1 + u_1 v_2 + u_2 v_1 + u_2 v_2) \\ &= d(u_1)v_1 + u_1 d(v_1) + d(u_1)v_2 + u_1 d(v_2) + d(u_2)v_1 + u_2 d(v_1) + d(u_2)v_2 + u_2 d(v_2) \\ &= (d(u_1) + d(u_2))v_1 + (u_1 + u_2)d(v_1) + (d(u_1) + d(u_2))v_2 + (u_1 + u_2)d(v_2) \\ &= d(u_1 + u_2)v_1 + 2ud(v_1) + d(u_1 + u_2)v_2 + 2ud(v_2) = d(2u)v_1 + 2u d(v_1) + d(2u)v_2 + 2ud(v_2) = 2c \\ &= 2d(u)2v + 2u d(2v) \\ &= 4d(u)v + 4u d(v). \end{aligned}$$

Thus $4d(uv) = 4(d(u)v + u d(v))$. Since R is 2-torsion free, we obtain

$d(uv) = d(u)v + u d(v)$. If U is a commutative σ -Lie ideal of R , then by Lemma 2.2, $U \subseteq Z$. Therefore, by using 2-torsion freeness of R and in view of the Lemma 1.1, we have

$$d(uv) = d(u)v + u d(v).$$

In view of above theorem, we obtain the following corollary.

Corollary 2.8 Let R be a 2-torsion free σ -prime ring. Then every Jordan derivations on R is a derivation on R .

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