

## THE HOMOLOGY AND COHOMOLOGY GROUPS OF $H_3$

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### ABSTRACT

A free resolution of  $\mathbf{Z}$  for the integral group ring of the three-dimensional Heisenberg group  $H_3$  has been constructed by extending Lyndon's partial resolution. The integral homology and cohomology have been calculated from there.

**AMS Classification:** 18G, 20J.

**Key words:** Fox derivatives, free resolution.

### 1. Introduction

Here we shall construct a full free resolution of  $\mathbf{Z}$  for the integral group ring of the three dimensional Heisenberg group, using Majumdar-Akhter [10] technique of extending Lyndon's partial free resolution [8] to a full free resolution. We compute the integral homology and cohomology from the resolution obtained.

$H_3$ , the three dimensional Heisenberg group has a presentation

$$H_3 = \langle x, y, z : [x, z] = [y, z] = 1, [x, y] = z \rangle, \text{ (Burillo [1], p.2).}$$

It is a member of widely studied important class of Lie Groups called the Heisenberg groups. It is nilpotent of class 2. Huebschmann [6] used his sophisticated perturbation theory technique to determine the cohomology of the generalized Heisenberg group given by

$$G = \langle x, y, z : [x, z] = [y, z] = 1, [x, y] = z^k \rangle.$$

$$G = H_3, \text{ if } k = 1.$$

The  $(2n+1)$  Heisenberg group  $H_{2n+1}$  is the group of upper triangular  $(n+2) \times (n+2)$  matrices of the form:

$$\begin{pmatrix} 1 & x & z \\ 0 & I & y^T \\ 0 & 0 & 1 \end{pmatrix},$$

where  $x = (x_1, x_2 \dots, x_n)$ ,  $y = (y_1, y_2 \dots, y_n)$ ,  $I$  is the  $n \times n$  unite matrix. Thus  $H_3$  is the group of all upper triangular matrices:

$$\begin{pmatrix} 1 & x & z \\ 0 & I & y \\ 0 & 0 & 1 \end{pmatrix}, (x, y, z \in \mathbb{R}).$$

The Heisenberg group  $H_3$  has a cubic Dehn function ([1], p.1) the latter being a best possible choice for isoperimetric function. Isoperimetric inequalities have been used fruitfully in the study of hyperbolic groups and automatic groups (Gromov [4], Epstein [2]). The cubic nature of Dehn function for  $H_3$  shows that it is neither hyperbolic nor automatic, since these have respectively a linear Dehn function and a quadratic Dehn function. Thurston proved this fact by combinatorial methods. He also shows that  $H_3$  is not combable

2. Before constructing our free resolution for  $H_3$ , we give a few definitions, state a few known results and prove a number of results that will be needed for construction and its proof.

**Lemma 2.1**

*$H_3$  is torsion free.*

**Proof**

$$H_3 = \left\{ \begin{pmatrix} 1 & x & z \\ 0 & I & y \\ 0 & 0 & 1 \end{pmatrix} : (x, y, z \in \mathbb{R}) \right\}.$$

Now 
$$\begin{pmatrix} 1 & x & z \\ 0 & I & y \\ 0 & 0 & 1 \end{pmatrix}^n = \begin{pmatrix} 1 & nx & nz + nxy \\ 0 & I & ny \\ 0 & 0 & 1 \end{pmatrix}.$$

So 
$$\begin{pmatrix} 1 & x & z \\ 0 & I & y \\ 0 & 0 & 1 \end{pmatrix}^n = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix},$$

if and only if  $n = 0$ .

Hence  $H_3$  is torsion free.

The following definitions are due to Higman [5].

**Definition 2.2**

A group  $G$  is said to be *indexed* if it can be mapped homomorphically onto a non-zero subgroup of  $\mathbf{Z}$ .

**Definition 2.3**

A group  $G$  is said to be *indicable throughout* if every subgroup  $H (\neq 1)$  of  $G$  can be indexed.

We state two theorems due to Higmann:

**Theorem 2.4** ([5], p.242)

*If  $G$  is indicable throughout and  $R$  is a ring with  $I$ , and has no zero divisors, then  $RG$  has no zero divisors.*

**Theorem 2.5** ([5], p. 243)

*If  $G$  is indicable throughout and  $R$  is a ring with  $I$  and has no zero divisors, then the units of  $RG$  are trivial.*

We shall use these results to prove:

**Theorem 2.6**

*$H_3$  is indicable throughout.*

**Proof**

We write  $G$  for  $H_3$  and let  $H(\neq 1)$  be a subgroup of  $G$ .

**Case I**

First suppose that  $H \subseteq G'$ . By the definition of  $G$ ,  $G'' \subseteq Z(G)$ . This implies that  $G'$  is abelian.  $G'$  is the normal subgroup generated by the commutator  $[h_1, h_2]$ ,  $h_1, h_2$  are the images of  $x_1, x_2$  in  $G$ . So a typical element  $g'$  of  $G'$  is  $\prod (g_i^{-1}([h_1, h_2]^{e_i}))$ ,  $e_i = 1$ .

$$\therefore g' = \prod_{i=1}^n [h_1, h_2]^{e_i}, \text{ since } [h_1, h_2] \text{ is a commutator of } h_1 \text{ and } h_2.$$

Since  $G'$  is infinite cyclic, and since  $H \neq 1$ ,  $H$  too infinite cyclic. So  $H$  can be indexed.

**Case II**

Suppose  $H \not\subseteq G'$ . Then  $HG' \neq G'$ , and so,  $\frac{HG'}{G'}$  is a subgroup of  $\frac{G'}{G'}$ , and is not the identity subgroup. Hence  $\frac{HG'}{G'}$  is free abelian. Then there is a homomorphism

$f: \frac{HG'}{G'} \rightarrow Z$  such that  $\text{Im} f \neq \{0\}$ . If  $\varphi$  is the canonical homomorphism  $\varphi: H \rightarrow \frac{HG'}{G'}$ , then

$\varphi$  is onto and  $\text{Im} \bar{f} \neq \{0\}$ , where  $\bar{f}: H \rightarrow Z$  is the composite  $\bar{f} = f\varphi$ . Thus  $H$  can be indexed.

Hence  $G$  is indicable throughout.

As a consequence of Theorem 2.4, Theorem 2.5 and Theorem 2.6 implies the following:

**Corollary 2.7**

*$ZG$  has no zero divisors.*

**Corollary 2.8**

The units of  $\mathbf{ZG}$  are trivial.

**3. Free resolution of  $\mathbf{Z}$** 

Let  $G = H_3 = \frac{F}{R}$ , where  $F$  is the free group generated by  $x_1, x_2$  and  $R$  is the normal

closure of  $r_1, r_2$ , where  $r_1 = [x_1, [x_1, x_2]]$  and  $r_2 = [x_2, [x_1, x_2]]$

i.e.,

$$\begin{aligned} r_1 &= x_1^{-1} x_2^{-1} x_1^{-1} x_2 x_1 x_1^{-1} x_2^{-1} x_1 x_2; \\ r_2 &= x_2^{-1} x_2^{-1} x_1^{-1} x_2 x_1 x_2 x_1^{-1} x_2^{-1} x_1 x_2. \end{aligned}$$

Then the Fox derivatives of  $r_1, r_2$  are:

$$\begin{aligned} \frac{\partial r_1}{\partial x_1} &= -r_1 - x_2 x_1 r_1 + x_2^{-1} x_1 x_2 + x_2; \\ \frac{\partial r_1}{\partial x_2} &= -x_1 r_1 + x_1 x_2^{-1} x_1 x_2 - x_2^{-1} x_1 x_2 + 1; \\ \frac{\partial r_2}{\partial x_1} &= -x_2^2 r_2 + x_2 x_1^{-1} x_2^{-1} x_1 x_2 - x_1^{-1} x_2^{-1} x_1 x_2 + x_2; \\ \frac{\partial r_2}{\partial x_2} &= -r_2 - x_2 r_2 + x_2^{-1} x_1 x_2^2 r_2 + x_1^{-1} x_2^{-1} x_1 x_2 - x_2^{-1} x_1 x_2 + 1. \end{aligned}$$

Writing  $\pi(x_i) = h_i, i = 1, 2$ , we have

$$\begin{aligned} \frac{\partial r_1}{\partial x_1} &= -1 - h_2 h_1 + h_2^{-1} h_1 h_2 + h_2; \\ \frac{\partial r_1}{\partial x_2} &= -h_1 + h_1 h_2^{-1} h_1 h_2 - h_2^{-1} h_1 h_2 + 1; \\ \frac{\partial r_2}{\partial x_1} &= -h_2^2 + h_2 h_1^{-1} h_2^{-1} h_1 h_2 - h_1^{-1} h_2^{-1} h_1 h_2 + h_2; \\ \frac{\partial r_2}{\partial x_2} &= -1 - h_2 + h_2^{-1} h_1 h_2^2 + h_1^{-1} h_2^{-1} h_1 h_2 - h_2^{-1} h_1 h_2 + 1. \end{aligned}$$

To construct the free resolution of  $\mathbf{Z}$  we proceed as follows. In Lyndon's partial free resolution of  $\mathbf{Z}$ , let  $\beta_1 \gamma_1 + \beta_2 \gamma_2 \in \text{Kerd}_1$ , where  $\gamma_1, \gamma_2 \in \mathbf{ZG}$ .

Then  $d_1(\beta_1 \gamma_1 + \beta_2 \gamma_2) = 0$ .

$$\begin{aligned} &\therefore \left[ \alpha_1 (h_2 - 1 - h_2 h_1 - h_2^{-1} h_1 h_2) + \alpha_2 (1 - h_1 - h_2^{-1} h_1 h_2 + h_1 h_2^{-1} h_1 h_2) \right] \gamma_1 \\ &+ \left[ \alpha_1 (-h_2^2 - h_2 h_1^{-1} h_2^{-1} h_1 h_2 - h_1^{-1} h_2^{-1} h_1 h_2 + h_2) + \alpha_2 (h_2^{-1} h_1 h_2^2 + h_1^{-1} h_2^{-1} h_1 h_2 - h_2^{-1} h_1 h_2 - h_2) \right] \gamma_2 \\ &= 0 \end{aligned}$$

$$\text{or, } \alpha_1 \left[ (h_2 - 1 - h_1 h_2 - h_2^{-1} h_1 h_2) \gamma_1 + (-h_2^2 - h_2 h_1^{-1} h_2^{-1} h_1 h_2 - h_1^{-1} h_2^{-1} h_1 h_2 + h_2) \gamma_2 \right] \\ + \alpha_2 \left[ (1 - h_1 - h_2^{-1} h_1 h_2 + h_1 h_2^{-1} h_1 h_2) \gamma_1 + (h_2^{-1} h_1 h_2^2 + h_1^{-1} h_2^{-1} h_1 h_2 - h_2^{-1} h_1 h_2 - h_2) \gamma_2 \right] = 0$$

Since  $Y_0$  is free on  $\alpha_1, \alpha_2$ , we have

$$\left. \begin{aligned} (h_2 - 1 - h_1 h_2 - h_2^{-1} h_1 h_2) \gamma_1 \\ + (-h_2^2 - h_2 h_1^{-1} h_2^{-1} h_1 h_2 - h_1^{-1} h_2^{-1} h_1 h_2 + h_2) \gamma_2 = 0 & \quad \text{(i)} \\ (1 - h_1 - h_2^{-1} h_1 h_2 + h_1 h_2^{-1} h_1 h_2) \gamma_1 \\ + (h_2^{-1} h_1 h_2^2 + h_1^{-1} h_2^{-1} h_1 h_2 - h_2^{-1} h_1 h_2 - h_2) \gamma_2 = 0 & \quad \text{(ii)} \end{aligned} \right\} \quad (3.1)$$

We write Equation (3.1) as

$$\left. \begin{aligned} a\gamma_1 + b\gamma_2 = 0 & \quad \text{(i)} \\ c\gamma_1 + d\gamma_2 = 0 & \quad \text{(ii)} \end{aligned} \right\} \quad \text{(i)}$$

Solving the equations (I) in  $\mathbf{Q}$ , we have  $\gamma_1 = \gamma'_1$ , where  $\gamma'_1$  is an arbitrary element of  $\mathbf{ZG}$ ,

and  $\gamma_2 = -b^{-1}a\gamma'_1 = -d^{-1}c\gamma'_1$ , so that  $-b^{-1}a = -d^{-1}c$ .  $\gamma'_1$  is an arbitrary element of  $\mathbf{ZG}$ ,  $-b^{-1}a = -d^{-1}c \in \mathbf{ZG}$ . Since  $b^{-1}a$  has an inverse  $a^{-1}b$ ,  $b^{-1}a = g_0$ , for some  $g_0 \in G$ , by Corollary 2.8.

Define  $Y_2$  as the right  $\mathbf{ZG}$ -module freely generated by  $\delta$  and define

$$d_2 : Y_2 \rightarrow Y_1 \quad \text{by}$$

$$d_2(\delta) = \beta_1 - \beta_2 g_0.$$

$$\text{Then } d_2(\delta \gamma_1) = (\beta_1 - \beta_2 g_0) \gamma_1 = \beta_1 \gamma_1 - \beta_2 g_0 \gamma_1 = \beta_1 \gamma_1 - \beta_2 \gamma_2.$$

$$\text{Hence } \beta_1 \gamma_1 + \beta_2 \gamma_2 \in \text{Ker} d_2.$$

$$\begin{aligned} \text{Also } (d_1 d_2)(\delta) &= d_1(\beta_1 - \beta_2 g_0) \\ &= (\alpha_1 a \gamma_1 + \alpha_2 a \gamma_2) - (\alpha_1 b g_0 \gamma_1 + \alpha_2 d g_0 \gamma_2) \\ &= \alpha_1(a - a) \gamma_1 + \alpha_2(c - c) \gamma_2 \\ &= 0 \end{aligned}$$

$$\therefore \text{Ker} d_2 \supseteq \text{Im} d_1.$$

Now let  $\delta \in \text{Ker} d_2$ , then

$$\alpha_1 \gamma - \alpha_2 g_0 \gamma = 0$$

$$\Rightarrow \gamma = 0.$$

Thus we have

**Theorem 3.1**

The following is a free  $\mathbf{ZG}$ -resolution of  $\mathbf{Z}$ :

$$0 \rightarrow Y_2 \xrightarrow{d_2} Y_1 \xrightarrow{d_1} Y_0 \xrightarrow{d_0} \mathbf{ZG} \xrightarrow{\varepsilon} \mathbf{Z} \rightarrow 0,$$

where  $Y_0, Y_1, Y_2$  are right  $\mathbf{ZG}$ -modules freely generated by  $\{\alpha_1, \alpha_2\}$ ,  $\{\beta_1, \beta_2\}$ ,  $\delta$  and

$\varepsilon, d_0, d_1, d_2$  are defined by

$$\varepsilon(g) = 1, \forall g \in G;$$

$$d_0(\alpha_1) = h_1 - 1;$$

$$d_0(\alpha_2) = h_2 - 1;$$

$$d_1(\beta_1) = \alpha_1(h_2 - 1 - h_2h_1 - h_2^{-1}h_1h_2) + \alpha_2(1 - h_1 - h_2^{-1}h_1h_2 + h_1h_2^{-1}h_1h_2)$$

$$d_1(\beta_2) = \alpha_1(-h_2^2 - h_2h_1^{-1}h_2^{-1}h_1h_2 - h_1^{-1}h_2^{-1}h_1h_2 + h_2)$$

$$+ \alpha_2(h_2^{-1}h_1h_2^2 + h_1^{-1}h_2^{-1}h_1h_2 - h_2^{-1}h_1h_2 - h_2).$$

$$d_2(\delta) = \beta_1 - \beta_2g_0.$$

**4. Homology**

For a left  $\mathbf{ZG}$ -module  $A$ , the homology groups  $H_n(G, A)$  are given by the homology of the complex of abelian groups

$$0 \rightarrow A \xrightarrow{\bar{d}_2} A^2 \xrightarrow{\bar{d}_1} A^2 \xrightarrow{\bar{d}_0} A \rightarrow 0,$$

where  $\bar{d}_0, \bar{d}_1, \bar{d}_2$  are given by

$$\bar{d}_0(a_2, a_2) = (h_1 - 1)a_1 + (h_2 - 1)a_2;$$

$$\bar{d}_1(a_1, a_2) = \left( \left[ h_2 - 1 - h_2h_1 - h_2^{-1}h_1h_2 \right] a_1,$$

$$\left[ -h_2^2 - h_2h_1^{-1}h_2^{-1}h_1h_2 - h_1^{-1}h_2^{-1}h_1h_2 + h_2 \right] a_2 \right)$$

$$\bar{d}_2(a) = (a, g_0a).$$

If  $A$  is trivial, then

$$\bar{d}_0(a_2, a_2) = 0;$$

$$\bar{d}_1(a_1, a_2) = (0, 0);$$

$$\bar{d}_2(a) = (a, a).$$

If  $A = \mathbf{Z}$ , then

$$\begin{aligned} H_0(G, Z) &\cong Z, \\ H_1(G, Z) &\cong Z \oplus Z, \\ H_2(G, Z) &\cong Z, \\ H_3(G, Z) &\cong 0. \end{aligned}$$

## 5. Cohomology

For a right  $\mathbf{ZG}$ -module  $A$ , the cohomology groups  $H^n(G, A)$  are given by the homology of the complex

$$0 \leftarrow A \xleftarrow{d_2^*} A^2 \xleftarrow{d_1^*} A^2 \xleftarrow{d_0^*} A \leftarrow 0,$$

where  $d_0^*, d_1^*, d_2^*$  are given by

$$\begin{aligned} d_0^*(a) &= (a(h_1 - 1), a(h_2 - 1)); \\ d_1^*(a_1, a_2) &= \left( a_1 \left[ h_2 - 1 - h_2 h_1 - h_2^{-1} h_1 h_2 \right], a_2 \left[ -h_2^2 - h_2 h_1^{-1} h_2^{-1} h_1 h_2 - h_1^{-1} h_2^{-1} h_1 h_2 + h_2 \right] \right), \\ d_2^*(a) &= a_1 - g_0 a_1. \end{aligned}$$

If  $A$  is trivial, then

$$\begin{aligned} d_0^*(a) &= (0, 0); \\ d_1^*(a_1, a_2) &= (0, 0) \\ d_2^*(a) &= 0. \end{aligned}$$

If  $A = Z$ , then

$$\begin{aligned} H^0(G, Z) &\cong Z, \\ H^1(G, Z) &\cong Z \oplus Z, \\ H^2(G, Z) &\cong Z \oplus Z, \\ H^3(G, Z) &\cong Z. \end{aligned}$$

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