



SORET AND DUFOUR EFFECTS ON MHD HEAT AND MASS TRANSFER FLOW OF A MICROPOLAR FLUID WITH THERMOPHORESIS PARTICLE DEPOSITION

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Abstract:

The effect of thermophoresis on heat and mass transfer flow of a micropolar fluid in the presence of Soret and Dufour effects over a stretching sheet is investigated in the present analysis. The transformed conservation equations are solved numerically using an optimized, extensively validated, variational Finite element method. The influence of key non-dimensional parameters, namely, suction parameter V_0 (0.1 - 0.5), magnetic parameter M (0.1-1.5), Soret parameter Sr (0.5 - 1.8), Dufour parameter Du (0.5 - 0.1) and thermophoretic parameter τ (0.1-1.5) on velocity, angular velocity (micro-rotation), temperature and concentration fields as well as skin-friction coefficient, Nusselt number and Sherwood number are examined in detail and the results are shown in graphically and in tabular form to know the physical importance of the problem. It is found that the imposition of wall fluid suction ($V_0 > 0$) in the present problem of flow has the effect of depreciating the velocity, micro-rotation, temperature and concentration boundary layer thicknesses at every finite value of η . The thermal boundary layer thickness decelerates whereas solutal boundary layer thickness is improved with the combined influence of Sr and Du .

Keywords: Micropolar fluid, Soret effect, Dufour effect, thermophoresis, finite element method

NOMENCLATURE

B_1	Coupling constant parameter	C	Concentration of the species
C_p	Specific heat at constant pressure	c_s	Concentration susceptibility
C_w	Uniform constant concentration	C_∞	Free stream concentration
K	Permeability parameter	M	Magnetic parameter
D_m	Mass diffusion coefficient	Du	Dufour number
E_c	Eckert Number	G	Acceleration due to gravity
G_r	Thermal Grashof number	G_m	Solutal Grashof number
G^*	Micropolar parameter	J	Microinertia density
k_p	Permeability of the porous medium	K_t	Thermal diffusion ratio
Nu	Nusselt number	Pr	Prandtl number
Sc	Schmidt number	Sh	Sherwood number
St	Shear stress	Sr	Soret number
Re	Local Reynolds number	T	Temperature of the fluid(K)
T_m	Mean fluid temperature(K)	T_w	Uniform temperature(K)
T_∞	Free stream temperature	U_0	Velocity at the wall(m/s)
V_1	Dimensionless suction velocity(m/s)	V_t	Thermophoretic velocity
u	Velocity in the x-direction(m/s)	v	Velocity in y-direction(m/s)
W	Microrotation (angular velocity) (m/s)		

Greek symbols

α	Thermal diffusivity	λ	Micropolar parameter
β	Coefficient of thermal expansion	ν	Kinematic viscosity($m^2 s^{-1}$)
β'	Coefficient of volume expansion	ρ	Density of the fluid(kgm^{-3})
γ	Spin gradient	σ	Electrical conductivity
θ	Non-dimensional temperature parameter	η	Similarity variable
τ	Thermophoretic parameter	ϕ	Non-dimensional concentration parameter
κ	Thermal conductivity($Wm^{-1}K$)	ω	Non-dimensional micro rotation parameter

1. Introduction

The theory of micropolar fluids has been an active area of research for several decades, because of its wide range of applications in analyzing fluid flow in brain, exotic lubricants, blood flow in animals, etc. Micropolar fluids are fluids with microstructure and related to the fluids with non-symmetrical stress tensor. They represent fluids consisting of rigid, randomly oriented or spherical particles suspended in a viscous medium, where the deformation of fluids particles is ignored (e.g. polymeric suspensions, animal blood, liquid crystals). The theory of micropolar fluids was originally formulated by Eringen (1966) by taking the local effects arising from the microstructure and the intrinsic motion of the fluid into the account. Micropolar fluids are non-Newtonian fluids consisting of dumb-bell molecules, colloidal fluids, liquid crystals, lubricants, suspension fluids, animal blood, etc. In this theory, the continuum is regarded as sets of structured particles which contain not only mass and velocity, but also a substructure. That is, each material volume element contains microvolume elements that can translate and rotate independently of the motion of microvolume. In this model, two independent kinematic vector fields are introduced — one representing the translation velocities of fluid particles; and the other representing angular (spin) velocities of the particles, called as microrotation vector. The more detail of this theory and its applications can be found in Ariman et al.(1973, 1974) and books by Lukaszewicz (1999) and Eringen (2001). Chamkha et al. (2010,2013) has presented unsteady MHD micropolar fluid past a heated vertical plate by considering Joule heating, radiation and chemical reaction effects. Bhargava et al. (2003) have presented heat and mass transfer characteristics of micropolar fluid over porous stretching sheet. Ibrahim et al. (2008) analyzed unsteady MHD mixed convection flow of a micropolar fluid by taking viscous dissipation and thermal radiation into the account. Damseh Rebhi et al. (2009) have noticed the influence of heat generation/absorption and first-order chemical reaction on micropolar fluid flow over a uniform stretching sheet. Pratap Kumar et al. (2010) have presented free convection flow of a micropolar fluid over a vertical plate. Yacos et al. (2011) have reported boundary layer heat transfer stagnation-point flow of micropolar fluid over a stretching/shrinking sheet. Rosali et al. (2012) analyzed micropolar fluid flow through porous media over a stretching/shrinking sheet with suction. Abd El-Aziz (2013) studied boundary layer flow and heat transfer analysis of a micropolar fluid over a stretching sheet with viscous dissipation and found that thermal boundary layer thickness decelerates with the higher values of micropolar parameter. Mahmood et al. (2013) have perceived boundary layer flow, heat transfer analysis of micropolar second grade fluid over a stretching sheet. Recently, Bala Siddulu Malga (2014) has analyzed the unsteady heat and mass transfer flow of a micropolar fluid over a vertical plate with thermal radiation and heat generation.

Thermophoresis is a phenomenon by which submicron sized particles suspended in a nonisothermal gas acquire a velocity relative to the gas in the direction of decreasing temperature. The velocity acquired by the particle is known as the thermophoretic velocity and the force experienced by the suspended particles due to the temperature gradient is called the thermophoretic force. The magnitudes of the thermophoretic force and velocity are proportional to the temperature gradient. Thermophoresis has many applications in radioactive particle deposition in nuclear reactors, deposition of silicon thin films, particles impacting the blade surface of gas turbines and aerosol technology. Many authors have done good work by taking thermophoresis in the account. Goren (1977) was first to analyze the thermophoresis in laminar flow over a flat plate for cold and hot plate conditions. Chamkha and Pop (2004, 2011a) analyzed the natural convection over a vertical flat plate in a porous medium with thermophoresis. Seddeek (2005) studied numerically the effect of variable viscosity and thermophoresis on a boundary layer flow with chemical reaction. Partha (2008, 2009) analyzed the effects of Soret and Dufour with thermophoresis in a non-Darcy porous medium, later he extended the problem by taking suction/injection in to the account.

The effects Thermo-diffusion and Diffusion-thermo are very significant for the fluids which have higher temperature and concentration gradients. The Thermo-Diffusion (Soret) effect is corresponds to species differentiation developing in an initial homogeneous mixture submitted to a thermal gradient and the Diffusion-thermo (Dufour) effect corresponds to the heat flux produced by a concentration gradient. Usually, in heat and mass transfer problems the variation of density with temperature and concentration give rise to a combined buoyancy force under natural convection and hence the temperature and concentration will influence the diffusion and energy of the species. Long years back, Chapman and Cowling (1952) and Hirshfelder et al. (1954) has been studied the effect of Thermo- diffusion and Diffusion-thermo of heat and mass transfer in the kinematic theory of gas. Alam et al. (2006a) have studied the Dufour and Soret effects on steady free convection and mass transfer flow past a semi-infinite vertical porous plate in a porous medium. Alam et al. (2006b) have

investigated, the effect of suction on mixed convective flow along vertical plate by taking Soret and Dufour effects. Dulal Pal et al. (2011) has studied MHD non-Darcian mixed convection heat and mass transfer over a non-linear stretching sheet with Soret and Dufour effects and chemical reaction. MHD mixed convection flow with Soret and Dufour effects past a vertical plate embedded in porous medium was studied by Makinde (2011). Chamkha et al. (2011b) have presented the impact of Soret and Dufour effects on unsteady natural convective flow over a vertical cylinder with chemical reaction. Reddy et al. (2012) has presented finite element solution to the heat and mass transfer flow past a cylindrical annulus with Soret and Dufour effects. Raju et al. (2014) have analyzed natural convection flow of Non-Newtonian fluid through porous medium by taking Soret effect into the consideration.

To the author knowledge no studies have been found in literature to analyze the combined influence of Soret and Dufour effects on convective heat and mass transfer flow of a viscous electrically conducting micropolar fluid over a stretching sheet in the presence of suction/injection and thermophoresis particle deposition. Hence, this problem is examined in this paper. The problem addressed in this article has many practical applications, such as, technological and manufacturing engineering, radioactive deposition of silicon thin films and polymer deposition of silicon thin films and polymer extrusion process. The equation of non-linear momentum, micro-rotation, temperature and concentration along with the boundary conditions are solved by using Finite element method with Mathematica 10.0 software.

2. Mathematical Formulation

We consider two-dimensional, study, mixed convective heat and mass transfer flow of a viscous electrically conducting, micropolar fluid through porous medium over a stretching sheet in the presence of thermophoresis, Soret and Dufour effects. The coordinate system is such that x -axis is taken along the stretching surface in the direction of the motion with the slot at origin, and the y -axis is perpendicular to the surface of the sheet as shown schematically in Fig. 1. A uniform transverse magnetic field (B_0) is applied along the y -axis. The stretching surface and the fluid are maintained same temperature and concentration initially, instantaneously they raised to a temperature $T_w (> T_\infty)$ and concentration $C_w (> C_\infty)$ which remain unchanged. The effects of thermophoresis are being taken in the diffusion equation to help in the understanding of the mass deposition variation on the surface. The temperature gradient in the y -direction is much larger than that in x -direction and hence thermophoretic velocity component normal to the surface is of more importance. Under the above stated physical situations, the governing boundary-layer and Darcy-Boussinesq's approximations, the basic equations are given by:

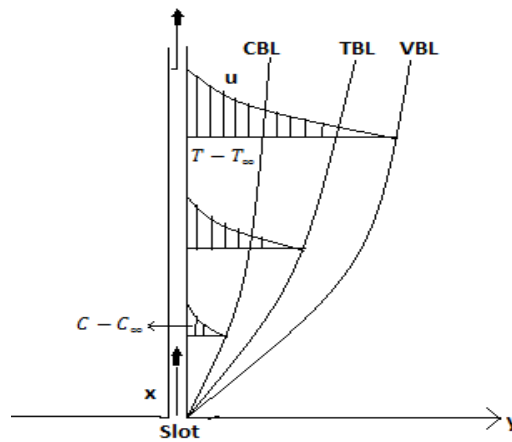


Fig. 1: Flow configuration and coordinate system.

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \tag{1}$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \nu \frac{\partial^2 u}{\partial y^2} + k_1 \frac{\partial W}{\partial y} + g_a \beta (T - T_\infty) + g_a \beta' (C - C_\infty) - \frac{\nu}{k_p} u + \frac{\sigma B_0^2}{\rho} u \tag{2}$$

$$u \frac{\partial W}{\partial x} + v \frac{\partial W}{\partial y} = -\frac{\kappa}{\rho J} \left(2W + \frac{\partial u}{\partial y} \right) + \frac{\gamma}{\rho J} \frac{\partial^2 W}{\partial y^2} \tag{3}$$

$$u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} = \alpha \frac{\partial^2 T}{\partial y^2} + \frac{\nu}{c_p} \left(\frac{\partial u}{\partial y} \right)^2 + \frac{D_m k_T}{c_s c_p} \frac{\partial^2 C}{\partial y^2} \tag{4}$$

$$u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} = D_m \frac{\partial^2 C}{\partial y^2} + \frac{D_m k_T}{T_m} \frac{\partial^2 T}{\partial y^2} - \frac{\partial}{\partial y} (V_T C) \tag{5}$$

The associated boundary conditions on the vertical surface are defined as follows,

$$u = U_w(x) = ax, \quad v = V_1(x), \quad T = T_w, \quad C = C_w, W = -s \left(\frac{\partial u}{\partial y} \right), \quad \text{at } y = 0.$$

$$u \rightarrow 0, \quad v \rightarrow 0, \quad T \rightarrow T_\infty, \quad C \rightarrow C_\infty, W \rightarrow 0, \quad \text{at } y \rightarrow \infty. \tag{6}$$

In the above equations x and y represents coordinate axis along the continuous surface in the direction of motion and perpendicular to it, u and v are the velocity components along x and y directions, respectively. The term

$V_1 = -\sqrt{\frac{vU_w}{2x}} V_0$ represents the mass transfer at the surface with $V_1 < 0$ for suction and $V_1 > 0$ for injection.

The effect of thermophoresis is usually prescribed by means of an average velocity acquired by small particles to the gas velocity when exposed to a temperature gradient. In boundary layer flow, the temperature gradient in y -direction is very much larger than in the x -direction and therefore only the thermophoretic velocity in y -direction is considered. As a consequence, the thermophoretic velocity V_T , which appears in Eq.(5), is expressed as

$$V_T = -\frac{K_1 v}{T_r} \frac{\partial T}{\partial y} \tag{7}$$

where K_1 is the thermophoretic coefficient and T_r is the reference temperature. A thermophoretic parameter τ is given by the relation

$$\tau = -\frac{K_1(T_w - T_\infty)}{T_r} \tag{8}$$

Where the typical values of τ are 0.01, 0.1 and 1.0 corresponding to approximate values of $-k_1(T_w - T_\infty)$ equal to 3, 30, 300K for a reference temperature of $T=300K$.

The mathematical analysis of the problem is simplified by introducing the following dimension less functions f, h, θ, φ and the similarity variable η

$$\eta = y \sqrt{\frac{a}{2\nu}}, \quad u = U_w \frac{df}{d\eta}, \quad v = -\sqrt{\frac{\nu U_w}{2x}} f(\eta) + \frac{U_w y}{2x} \frac{df}{d\eta},$$

$$W = -\sqrt{\frac{U_w}{2\nu x}} U_w h, \quad \theta(\eta) = \frac{T - T_\infty}{T_w - T_\infty}, \quad \varphi(\eta) = \frac{C - C_\infty}{C_w - C_\infty}. \tag{9}$$

The continuity equation (1) is satisfied by the stream function $\psi(x, y)$ defined by

$$u = \frac{\partial \psi}{\partial y}, \quad v = -\frac{\partial \psi}{\partial x} \tag{10}$$

Substituting Eqn. (9) in Eqns. (2) to (6), we obtain

$$f''' + B_1 h' + f f'' + G_r \theta + G_m \varphi - K f' - M f' = 0 \tag{11}$$

$$\lambda h'' - 2 \frac{\lambda}{G_1} (2h + f'') + f' h + f h' = 0 \tag{12}$$

$$\theta'' + Pr f \theta' + Pr Du \varphi'' + Pr Ec (f'')^2 = 0 \tag{13}$$

$$\varphi'' + Sc f \varphi' + Sc Sr \theta'' - \tau (\theta' \varphi' + \theta'' \varphi) = 0 \tag{14}$$

Where $\lambda = \frac{\gamma}{\rho \nu}$ and $G_1 = \frac{\gamma a}{\nu k}$ are micropolar parameters, $G_r = \frac{2g_a \beta x}{U_w^2} (T_w - T_\infty)$ is local Grashof number ,

$G_m = \frac{2g_a \beta' x}{U_w^2} (C_w - C_\infty)$ is local modified Grashof number , $B_1 = \frac{K_1}{\nu}$ is the Coupling constant parameter,

$K = \frac{U_w k_p}{2\nu x}$ is the permeability parameter, $Pr = \frac{\nu}{\alpha}$ is the Prandtl number, $Sc = \frac{\nu}{D_m}$ is the Schmidt number,

$Du = \frac{D_m k_T}{c_s c_p \nu} \frac{(C_w - C_\infty)}{(T_w - T_\infty)}$; is the Dufour number, $Sr = \frac{D_m k_T}{\nu T_m} \frac{(T_w - T_\infty)}{(C_w - C_\infty)}$; is the Soret number, $Ec = \frac{U_w^2}{c_p} \frac{1}{(T_w - T_\infty)}$ is the Eckert

number, $\nu = \frac{\mu + \kappa}{\rho}$ is the kinematic viscosity, $k_1 = \frac{\kappa}{\rho} (k_1 > 0)$ is the coupling constant,

$M = \frac{2\sigma B_0^2 x}{\rho U_w}$ is the magnetic parameter.

The corresponding transformed boundary conditions are

$$f' = 1, f = V_0, h = -s f'', \theta = 1, \varphi = 1, \quad \text{at } y = 0$$

$$f' = 0, h = 0, \theta = 0, \varphi = 0 \quad \text{at } y \rightarrow \infty \tag{15}$$

Where $f(0) = V_0$ with $V_0 < 0$ and $V_0 > 0$ corresponding to injection and suction respectively.

The major physical quantities of interest in this problem are the local skin friction coefficient (C_f), the local Nusselt number (Nu_x) and the local Sherwood number (Sh_x) are defined, respectively, by

$$C_f = \frac{f''(0)}{Re_x^{\frac{1}{2}}}, Nu_x = -\frac{\theta'(0)}{Re_x^{\frac{1}{2}}}, Sh_x = -\frac{\phi'(0)}{Re_x^{\frac{1}{2}}} \tag{16}$$

3. Method of Solution

3.1 Finite Element Method

The Finite- element method (FEM) has been implemented to obtain numerical solutions of coupled non-linear equations (11) to (14) of third-order in f and second order in h, θ, ϕ under boundary conditions (15). This technique is extremely efficient and allows robust solutions of complex coupled, nonlinear multiple degree differential equation systems. The details of finite-element method can find in Bhargava et al. (2009), Anwar Beg et al. (2008) and Rana et al. (2012). The steps involved in this method are as follows:

(i) *Finite-element discretization*

In the finite element discretization the entire interval is divided into a finite number of subintervals and this subinterval is called an element. The set of all these elements is called the finite-element mesh.

(ii) *Generation of the element equations*

- a. Variational formulation of the mathematical model over the typical element (an element from the mesh) is performed.
- b. An approximate solution of the variational problem is assumed, and the element equations are made by substituting this solution in the above system.
- c. Using interpolating polynomials the stiffness matrix is constructed.

(iii) *Assembly of element equations*

By imposing inter element continuity conditions all the algebraic equations are assembled. This result a large number of algebraic equations called global finite-element model and it represents the whole domain.

(iv) *Imposition of boundary conditions*

The boundary conditions which represent the flow model are imposed on the assembled equations.

(v) *Solution of assembled equations*

The assembled equations so obtained can be solved by any of the numerical techniques, namely, the Gauss elimination method, LU decomposition method, etc. An important consideration is that of the shape functions which are employed to approximate actual functions.

For the solution of system of non-linear ordinary differential equation (11) – (14) together with boundary conditions (15), first we assume that

$$\frac{df}{d\eta} = j \tag{17}$$

The equations (11) to (14) then reduces to

$$j'' + B_1 h' + f j' + G_r \theta + G_m \phi - (K + M)j = 0 \tag{18}$$

$$\lambda h'' - 2 \frac{\lambda}{G_1} (2h + j') + j h + f h' = 0 \tag{19}$$

$$\theta'' + Pr f \theta' + Pr Du \phi'' + Pr Ec (j')^2 = 0 \tag{20}$$

$$\phi'' + Sc f \phi' + Sc Sr \theta'' - \tau(\theta' \phi' + \theta'' \phi) = 0 \tag{21}$$

The boundary conditions take the form

$$\begin{aligned} j = 1, f = V_0, h = -s j', \theta = 1, \phi = 1, \text{ as } y = 0 \\ j = 0, h = 0, \theta = 0, \phi = 0, \text{ as } y \rightarrow \infty \end{aligned} \tag{22}$$

3.2. Variational formulation

The variational form associated with Eqs. (17) to (21) over a typical linear element (η_e, η_{e+1}) is given by

$$\int_{\eta_e}^{\eta_{e+1}} w_1 \left(\frac{df}{d\eta} - j \right) d\eta = 0 \tag{23}$$

$$\int_{\eta_e}^{\eta_{e+1}} w_2 (j'' + B_1 h' + f j' + G_r \theta + G_m \phi - (K + M)j) d\eta = 0 \tag{24}$$

$$\int_{\eta_e}^{\eta_{e+1}} w_3 \left(\lambda h'' - 2 \frac{\lambda}{G_1} (2h + j') + j h + f h' \right) d\eta = 0 \tag{25}$$

$$\int_{\eta_e}^{\eta_{e+1}} w_4 (\theta'' + Pr f \theta' + Pr Du \phi'' + Pr Ec (j')^2) d\eta = 0 \tag{26}$$

$$\int_{\eta_e}^{\eta_{e+1}} w_5 (\phi'' + Sc f \phi' + Sc Sr \theta'' - \tau(\theta' \phi' + \theta'' \phi)) d\eta = 0 \tag{27}$$

Where w_1, w_2, w_3, w_4 and w_5 are arbitrary test functions and may be viewed as the variations in $f, h, \theta,$ and $\phi,$ respectively.

3.3. Finite- element formulation

The finite-element model may be obtained from above equations by substituting finite-element approximations of the form

$$f = \sum_{j=0}^2 f_j \Psi_j, \quad j = \sum_{j=0}^2 j_j \Psi_j, \quad h = \sum_{j=0}^2 h_j \Psi_j, \quad \theta = \sum_{j=0}^2 \theta_j \Psi_j, \quad \phi = \sum_{j=0}^2 \phi_j \Psi_j. \quad (28)$$

With $w_1 = w_2 = w_3 = w_4 = w_5 = \Psi_i$, $(i = 1,2)$.

Where Ψ_i are the shape functions for a typical element (η_e, η_{e+1}) and are defined as

$$\Psi_1^e = \frac{(\eta_{e+1}-\eta)}{(\eta_{e+1}-\eta_e)}, \quad \Psi_2^e = \frac{(\eta-\eta_e)}{(\eta_{e+1}-\eta_e)}, \quad \eta_e \leq \eta \leq \eta_{e+1}. \quad (29)$$

The finite element model of the equations thus formed is given by

$$\begin{bmatrix} [K^{11}] & [K^{12}][K^{13}] & [K^{14}][K^{15}] \\ [K^{21}] & [K^{22}][K^{23}] & [K^{24}][K^{25}] \\ [K^{31}] & [K^{32}][K^{33}] & [K^{34}][K^{35}] \\ [K^{41}] & [K^{42}][K^{43}] & [K^{44}][K^{45}] \\ [K^{51}] & [K^{52}][K^{53}] & [K^{54}][K^{55}] \end{bmatrix} \begin{bmatrix} f \\ j \\ h \\ \theta \\ \phi \end{bmatrix} = \begin{bmatrix} \{r^1\} \\ \{r^2\} \\ \{r^3\} \\ \{r^4\} \\ \{r^5\} \end{bmatrix}$$

Where $[K^{mn}]$ and $\{r^m\}$ ($m, n = 1, 2, 3, 4,5$) are defined as

$$K_{ij}^{11} = \int_{\eta_e}^{\eta_{e+1}} \psi_i \frac{\partial \psi_j}{\partial \eta} d\eta, \quad K_{ij}^{12} = - \int_{\eta_e}^{\eta_{e+1}} \psi_i \psi_j d\eta, \quad K_{ij}^{13} = K_{ij}^{14} = K_{ij}^{15} = 0.$$

$$K_{ij}^{21} = \int_{\eta_e}^{\eta_{e+1}} \psi_i \frac{\partial \psi_j}{\partial \eta} d\eta, \quad K_{ij}^{22} = - \int_{\eta_e}^{\eta_{e+1}} \frac{\partial \psi_i}{\partial \eta} \frac{\partial \psi_j}{\partial \eta} d\eta + (M + K) \int_{\eta_e}^{\eta_{e+1}} \psi_i \psi_j d\eta,$$

$$K_{ij}^{23} = B_1 \int_{\eta_e}^{\eta_{e+1}} \psi_i \frac{\partial \psi_j}{\partial \eta} d\eta, \quad K_{ij}^{24} = G_r \int_{\eta_e}^{\eta_{e+1}} \psi_i \psi_j d\eta, \quad K_{ij}^{25} = G_m \int_{\eta_e}^{\eta_{e+1}} \psi_i \psi_j d\eta.$$

$$K_{ij}^{31} = \int_{\eta_e}^{\eta_{e+1}} \psi_i \frac{\partial \psi_j}{\partial \eta} d\eta, \quad K_{ij}^{32} = 2 \frac{\lambda}{G_1} \int_{\eta_e}^{\eta_{e+1}} \psi_i \frac{\partial \psi_j}{\partial \eta} d\eta + \int_{\eta_e}^{\eta_{e+1}} \psi_i \psi_j d\eta.$$

$$K_{ij}^{33} = \lambda \int_{\eta_e}^{\eta_{e+1}} \psi_i \frac{\partial \psi_j}{\partial \eta} d\eta + 4 \frac{\lambda}{G_1} \int_{\eta_e}^{\eta_{e+1}} \psi_i \psi_j d\eta, \quad K_{ij}^{34} = K_{ij}^{35} = 0.$$

$$K_{ij}^{41} = Pr \int_{\eta_e}^{\eta_{e+1}} \psi_i \frac{\partial \psi_j}{\partial \eta} d\eta, \quad K_{ij}^{42} = Pr.Ec \int_{\eta_e}^{\eta_{e+1}} \psi_i \frac{\partial \psi_j}{\partial \eta} \frac{\partial \psi_j}{\partial \eta} d\eta, \quad K_{ij}^{43} = 0,$$

$$K_{ij}^{44} = \int_{\eta_e}^{\eta_{e+1}} \psi_i \bar{\theta} \frac{\partial \psi_j}{\partial \eta} d\eta, \quad K_{ij}^{45} = Pr Du \int_{\eta_e}^{\eta_{e+1}} \psi_i \bar{\phi} \frac{\partial \psi_j}{\partial \eta} d\eta,$$

$$K_{ij}^{51} = Sc \int_{\eta_e}^{\eta_{e+1}} \psi_i \bar{\phi} \psi_j d\eta, \quad K_{ij}^{52} = 0, \quad K_{ij}^{53} = 0,$$

$$K_{ij}^{54} = Sc Sr \int_{\eta_e}^{\eta_{e+1}} \psi_i \bar{\theta} \frac{\partial \psi_j}{\partial \eta} d\eta - \tau \int_{\eta_e}^{\eta_{e+1}} \psi_i \bar{\theta} \frac{\partial \psi_j}{\partial \eta} \psi_j d\eta, \quad K_{ij}^{55} = \int_{\eta_e}^{\eta_{e+1}} \frac{\partial \psi_i}{\partial \eta} \frac{\partial \psi_j}{\partial \eta} d\eta - \tau \int_{\eta_e}^{\eta_{e+1}} \psi_i \frac{\partial \psi_j}{\partial \eta} d\eta.$$

$$r_i^2 = 0, \quad r_i^2 = - \left(\psi_i \frac{d\Psi_i}{d\eta} \right)_{\eta_e}^{\eta_{e+1}}, \quad r_i^3 = - \left(\psi_i \frac{d\Psi_i}{d\eta} \right)_{\eta_e}^{\eta_{e+1}}, \quad r_i^4 = - \left(\psi_i \frac{d\Psi_i}{d\eta} \right)_{\eta_e}^{\eta_{e+1}}, \quad r_i^5 = - \left(\psi_i \frac{d\Psi_i}{d\eta} \right)_{\eta_e}^{\eta_{e+1}}$$

Where

$$\bar{f} = \sum_{j=0}^2 f_j \frac{\partial \Psi_i}{\partial \eta}, \quad \bar{j} = \sum_{j=0}^2 j_j \frac{\partial \Psi_i}{\partial \eta}, \quad \bar{h} = \sum_{j=0}^2 h_j \frac{\partial \Psi_i}{\partial \eta}, \quad \bar{\theta} = \sum_{j=0}^2 \theta_j \frac{\partial \Psi_i}{\partial \eta}, \quad \bar{\phi} = \sum_{j=0}^2 \phi_j \frac{\partial \Psi_i}{\partial \eta}.$$

The very important aspect in this numerical procedure is to select an approximate finite value of η_∞ . So, in order to estimate the relevant value of η_∞ , the solution process has been started with an initial value of $\eta_\infty = 4$, and then Equations (23) – (27) are solved together with associated boundary conditions. We have updated the value of η_∞ and the solution process is continued until the results are not affected with further values of η_∞ . The choice of $\eta_{max} = 4$ for velocity and temperature and $\eta_{max} = 6$ for concentration have confirmed that all the numerical solutions approach to the asymptotic values at the free stream conditions.

4. Grid Independence Test

To investigate the sensitivity of the solutions to mesh density, we have performed the grid invariance test for velocity, temperature and concentration distributions and are shown in table 1. It is observed from this table that in the same domain the accuracy is not affected, even the number of elements increased, by decreasing the size of the elements.

5. Results and Discussion

Comprehensive numerical computations were conducted for different values of the parameters and results are illustrated graphically as well as in tabular form. Selected computations are presented in Figs. 2-12. The correctness of the current numerical method is checked with the results obtained by Mohanty et al. (2015) and is

shown in table 2. Thus, it is seen from table 2 that the numerical results are in close agreement with those published previously.

5.1 Effect of suction (V_0)

Fig.2 illustrates the variation of velocity profiles for various values of suction parameter (V_0). It is observed from this figure that the velocity decreases with increase in the value of the suction parameter. This is because of the reality that the momentum boundary layer thickness depreciates with increment in (V_0). Further, it is seen that the velocity decreases with increase in η till it satisfies the boundary condition at $\eta \rightarrow \infty$. Fig.3 illustrates the effect of (V_0) on micro-rotation profiles. Since there is no buoyancy term occurs in the angular momentum equation, then there exist strong coupling between translational velocity and micro-rotation fields. The linear momentum equation (11) also contains the micro-rotation term, which further gives coupling between velocity and angular velocity fields. All the profiles have different values at $\eta = 0$ because of the initial condition $h(0) = -sf''(0)$ which is always non-zero since $s = 0.5$ and $f''(0) \neq 0$. The effect of (V_0) on temperature profiles (θ) is shown in Fig.4. It is seen from this figure that temperature profiles decreases with increase in the values of (V_0). This is due to the fact that the presence of wall suction has the tendency to reduce the thermal boundary layer thickness which results the reduction in the temperature profiles. Fig.5 depicts the changes in concentration profiles for different values of suction parameter (V_0). This figure indicates that increase in suction parameter (V_0) decreases concentration profiles and is because of the imposition of suction/injection parameter into the flow region depreciate the concentration of the species in the solutal boundary layer. Therefore, From the above Figs. 2 - 5 we observed that the imposition of wall fluid suction ($V_0 > 0$) in the present problem of flow has the effect of depreciating the velocity, micro-rotation, temperature and concentration boundary layer thicknesses at every finite value of η . The deceleration in all profiles with the higher values of suction parameter ($V_0 > 0$) is from the reality that suction is taken away the warm fluid from the fluid region.

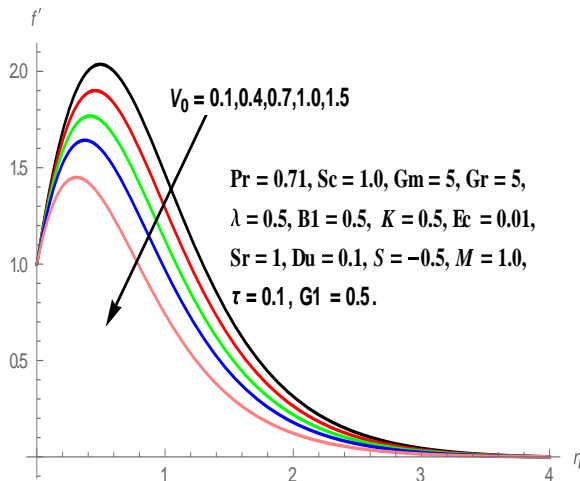


Fig. 2: Effect of V_0 on velocity profile.

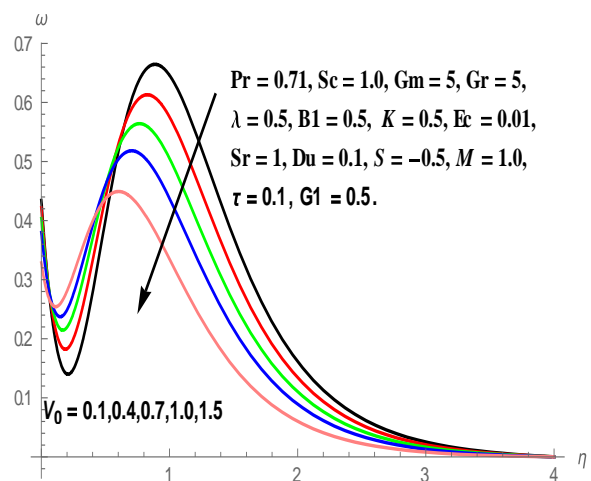


Fig. 3: Effect of V_0 on micro-rotation profile

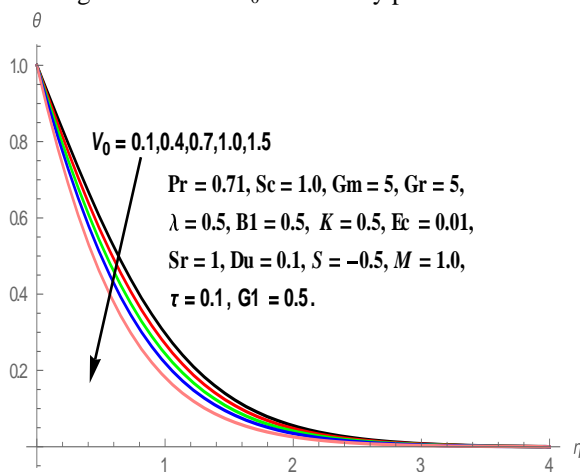


Fig. 4: Effect of V_0 on temperature profile.

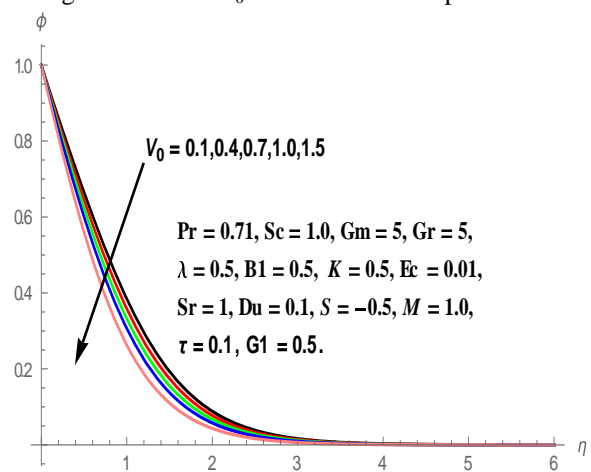


Fig. 5: Effect of V_0 on concentration profile

The variation of local skin-friction co-efficient ($f''(0)$), local Nusselt number ($-\theta'(0)$), and local Sherwood number ($-\phi'(0)$) for different values of suction parameter (V_0) is presented in table 3. It is seen from table that the local skin-friction co-efficient depreciates whereas the dimensionless heat and mass transfer rates elevates with increase in suction parameter (V_0).

5.2 Effect of magnetic parameter (M)

The influence of magnetic field parameter (M) on velocity, temperature and concentration profiles in the boundary layer is depicted in Figs. 6 - 8. It is noticed from these figures that the hydrodynamic boundary layer thickness depreciates, whereas the thermal boundary layer thickness as well as the solutal boundary layer thickness enhances with the higher values of (M). This is because of the reality that, the presence of magnetic field in an electrically conducting fluid produces a force called Lorentz force, this force acts against the flow direction causes the depreciation in velocity profiles (fig. 6), and at the same time, to overcome the drag force imposed by the Lorentzian retardation the fluid has to perform extra work; this supplementary work can be converted into thermal energy which increases the thickness of thermal and solutal boundary layers in the fluid region (figs. 7 & 8).

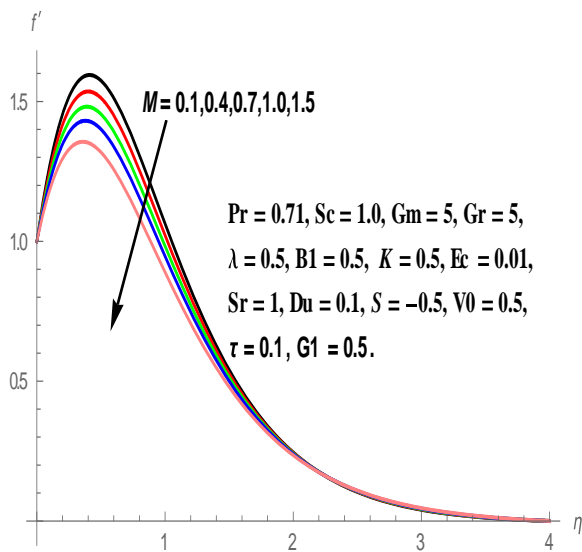


Fig. 6: Effect of M on velocity profile.

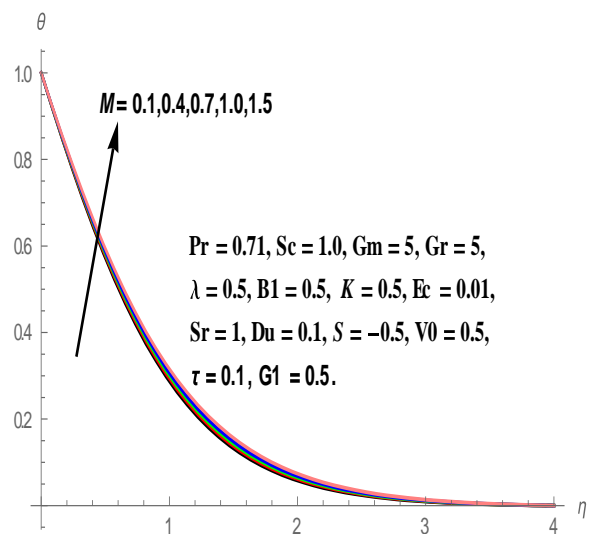


Fig. 7: Effect of M on temperature profile.

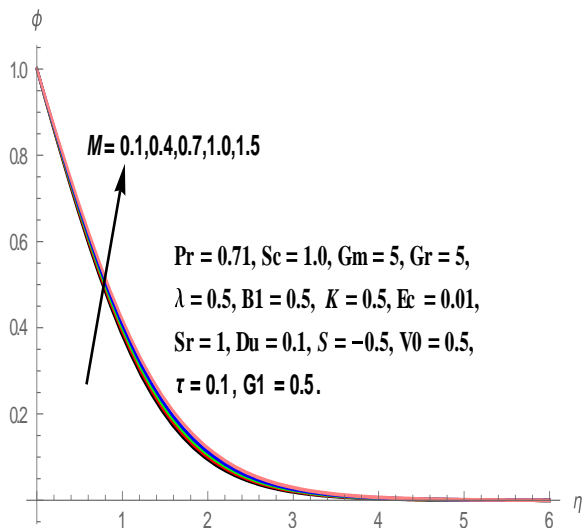


Fig. 8: Effect of M on concentration profile

The sway of magnetic parameter (M) on skin-friction coefficient, Nusselt number and Sherwood number is also presented in table 3. It is clear from this table that skin-friction coefficient, dimensionless heat and mass transfer rates are all decelerates with the higher values of magnetic parameter (M).

5.3 Effect of Soret and Dufour parameters (Sr & Du)

The combined impact of (Sr) and (Du) on temperature and concentration profiles is depicted in Figs. 9-10. In these graphs (Sr) and (Du) values are taken as $Sr = 0.5, 0.8, 1.1, 1.4, 1.8$ and $Du = 0.5, 0.3, 0.2, 0.15, 0.1$. It is clearly observed from these graphs that the temperature distributions decreases whereas concentration profiles increases at all points in the flow field with the increasing values of Soret number (Sr) and the decreasing values of Dufour parameter (Du). This is because of the fact that the diffusive species with higher values of Soret parameter (Sr) has the tendency of increasing concentration profiles whereas thermal species with lower Dufour parameter (Du) values has the tendency of depreciating temperature profiles in the flow field. Thus, it is concluded from Figs. 9 - 10 that the temperature and concentration distributions are more influenced with the values of Soret and Dufour parameters.

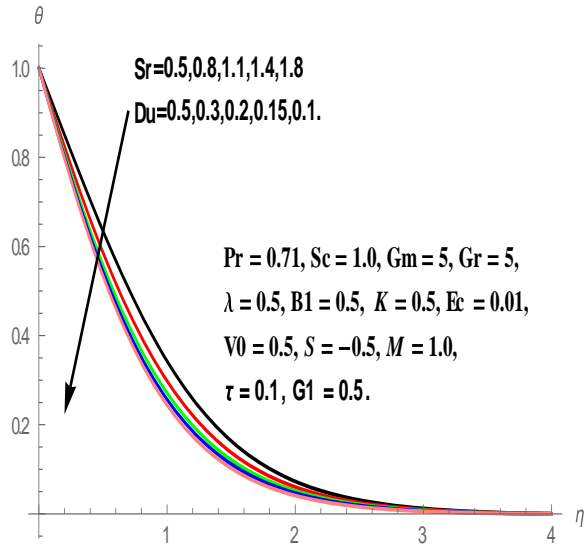


Fig.9: Effect of Sr & Du on temperature profile

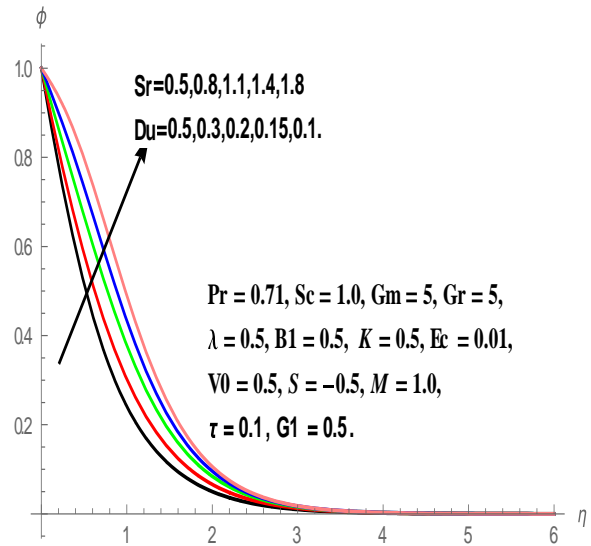


Fig.10: Effect of Sr & Du on concentration profile

The combined influence of (Sr) and (Du) on skin-friction coefficient, Nusselt number and Sherwood number is also reported in table 3. It is noticed that $f''(0)$ and the dimensionless heat transfer rates are both improved whereas the dimensionless mass transfer rates falls with the increasing values of (Sr) and decreasing values of (Du).

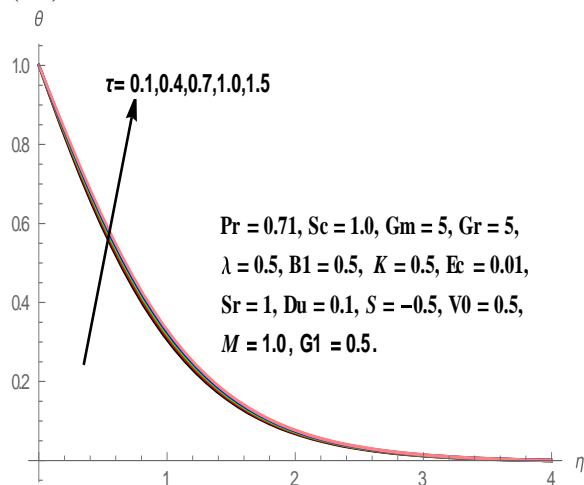


Fig. 11: Effect of τ on temperature profile

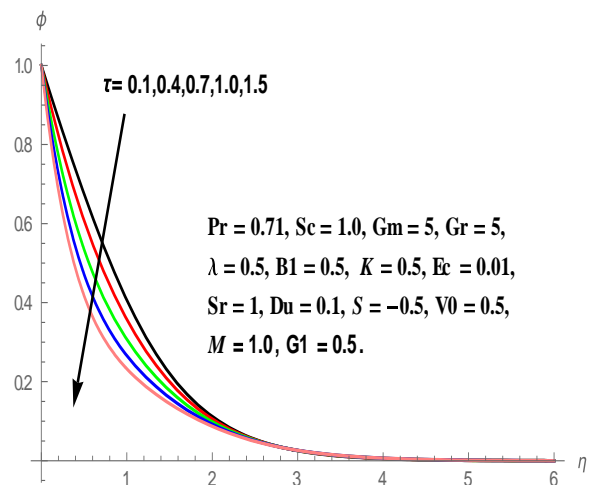


Fig. 12: Effect of τ on concentration profile

5.4 Effect of thermophoretic parameter (τ)

The variation in temperature and concentration distributions for various values of thermophoretic parameter τ is depicted in Figs.11 and 12. It is seen from fig.11 that the thickness of the thermal boundary layer increases in flow region with higher values of thermophoretic parameter (τ). This is because of the fact that the particles near the hot surface create a thermophoretic force causes the increment in the thermal boundary layer thickness.

However, the thickness of solutal boundary layers depreciates in the entire flow region with increase in the values of thermophoretic parameter (τ).

It is evident from table 3 that the skin-friction co-efficient and Nusselt number depreciates whereas Sherwood number enhances with the increasing values of thermophoresis parameter (τ).

7. Conclusion

In the present analysis we have investigated the combined influence of suction and thermophoresis on the mixed convective heat and mass transfer boundary layer flow of a micropolar fluid through porous medium over a stretching sheet in the presence of Thermo-Diffusion and Diffusion-Thermo effects. Similarity transformation is used to transform the resulting partial differential equations into the set of highly non-linear ordinary differential equations and are solved numerically by using Finite element method. The most significant findings of the present study are as follows.

- The velocity, micro-rotation, temperature and concentration profiles are highly influenced with different values of magnetic parameter (M). Velocity profiles impedes because of the Laurentz force, whereas the thickness of thermal and concentration boundary layers are both elevates with higher values of M .
- The thickness of hydrodynamic, microrotation, thermal and solutal boundary layers is reduced with the higher values of suction parameter (V_0). This is because of the fact that suction is taken away the warm fluid from the fluid region.
- The thermal boundary layer thickness is improved with the increasing values of thermophoretic parameter (τ). This is because of the fact that thermophoresis acts against temperature gradient, so that, the particles move from the region of higher temperature to the region of lower temperature.
- The rates of non-dimensionless temperature decreases with an increase in the values of Soret number Sr .
- The rate of non-dimensionless concentration improves with increasing values of Soret parameter (Sr).
- The Nusselt number increases with the decreasing values of Dufour number (Du).

Table 1:Grid-invariance test for velocity distribution (f'), temperature distribution (θ) and concentration distribution (φ), for $\lambda=0.5, G_1=0.5, Ec=0.01, B_1=0.5, M=1.0, \tau = 0.1, Pr=0.71, Sc = 0.22, K= 0.5, V_0 = 0.5, Gm = 0.1, Gr = 1.0, Sr=1.0, Du=0.1$.

η	f'				θ				φ			
	Step size (h)											
	0.04	0.02	0.01	0.005	0.04	0.02	0.01	0.005	0.04	0.02	0.01	0.005
0.0	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000
1.0	1.4364	1.2563	1.1157	1.1154	0.3174	0.2849	0.2446	0.2445	0.3874	0.3457	0.3289	0.3286
2.0	0.3172	0.2965	0.1874	0.1873	0.0532	0.0321	0.0318	0.0317	0.0965	0.0824	0.0816	0.0814
3.0	0.0534	0.0425	0.0264	0.02631	0.0056	0.0041	0.0011	0.0010	0.0156	0.0098	0.0084	0.0083
4.0	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0054	0.0041	0.0034	0.0032
5.0	----	----	----	----	----	----	----	----	0.0005	0.0003	0.0002	0.0001
6.0	----	----	----	----	----	----	----	----	0.0000	0.0000	0.0000	0.0000

Table 2:Comparison of local Skin-friction, Nusselt number and Sherwood number with the existing results, when $Sr = 0, Du = 0, G_1 = 0.5, V_0 = 0, B_1 = 0.1, \tau = 0, \lambda = 0.5$.

Parameter							C_f		Nu_x		Sh_x	
Gr	Gc	Pr	Sc	M	K	Ec	Mohanty et al. (2015)	Present Study	Mohanty et al. (2015)	Present Study	Mohanty et al. (2015)	Present Study
0.0	0.0	0.72	0.00	0	100	0.00	-0.81861	-0.81873	0.85604	0.85619	0.16666	0.16671
0.1	0.0	0.72	0.00	0	100	0.00	-0.78025	-0.78019	0.86514	0.86526	0.42252	0.42263
0.1	0.0	0.72	0.22	0	100	0.00	-0.78025	-0.78019	0.86514	0.86526	0.42252	0.42263
0.1	0.0	0.72	0.22	1	100	0.00	-1.11781	-1.11776	0.78477	0.78482	0.37866	0.37872
0.1	0.0	0.72	0.22	1	0.5	0.01	-1.59782	-1.59773	0.68391	0.68386	0.33393	0.33385
0.1	0.0	0.72	0.22	1	100	0.01	-1.11775	-1.11766	0.77999	0.77981	0.37867	0.37874
0.1	0.0	0.72	0.22	1	0.5	0.01	-1.59777	-1.59782	0.67651	0.67646	0.33394	0.33398
0.1	0.1	7.00	0.22	1	100	0.01	-1.09307	-1.09311	3.02046	3.02052	0.38361	0.38370
0.5	0.1	0.72	0.22	1	100	0.01	-0.93986	-0.93991	0.82922	0.82931	0.40495	0.40486
0.1	0.1	0.72	0.22	1	100	0.01	-1.06792	-1.06798	0.79858	0.79863	0.38891	0.38896
0.5	0.1	0.72	0.22	1	0.5	0.01	-1.44651	-1.44667	0.72576	0.72569	0.35583	0.35591

Table 3: The local Skin-friction, Nusselt number and Sherwood number for different values of the important parameters.

V_0	M	Sr	Du	τ	$f''(0)$	$-\theta'(0)$	$-\phi'(0)$
0.1	1.0	1.0	0.1	0.1	4.341664	0.840417	0.713787
0.4	1.0	1.0	0.1	0.1	4.217637	0.957082	0.766098
0.7	1.0	1.0	0.1	0.1	4.035646	1.081757	0.820302
1.0	1.0	1.0	0.1	0.1	3.797455	1.214205	0.877212
0.5	0.1	1.0	0.1	0.1	3.181322	0.956905	0.727742
0.5	0.4	1.0	0.1	0.1	2.951362	0.946389	0.714376
0.5	0.7	1.0	0.1	0.1	2.735015	0.936191	0.701742
0.5	1.0	1.0	0.1	0.1	2.531069	0.926322	0.689786
0.5	1.0	0.5	0.5	0.1	4.073383	0.743463	1.165773
0.5	1.0	0.8	0.3	0.1	4.130123	0.897880	0.960502
0.5	1.0	1.1	0.2	0.1	4.304030	0.985056	0.688923
0.5	1.0	1.4	0.1	0.1	4.304302	1.025185	0.482014
0.5	1.0	1.0	0.1	0.1	2.531069	0.926322	0.689786
0.5	1.0	1.0	0.1	0.4	2.403028	0.899578	0.967457
0.5	1.0	1.0	0.1	0.7	2.262505	0.867547	1.307852
0.5	1.0	1.0	0.1	1.0	2.140653	0.837243	1.637596

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